

OmniSTAR.

3200LR12 Receiver



User Manual



Issue 1.5 June 2005

3200LR12 RECEIVER USER MANUAL

Notice to Customers

This manual has been produced to ensure the very best performance from your OmniSTAR receiver. The manual has been clearly set out with simple instructions to ensure trouble free usage of your OmniSTAR receiver.

This publication could contain technical inaccuracies or typographical errors. Changes are periodically made to the information herein; these changes will be incorporated in new editions of this publication.

Should you require further assistance please contact your local dealer or the OmniSTAR B.V. office.

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**3200LR12 RECEIVER
USER MANUAL**

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One-Year Limited Hardware Warranty

OmniSTAR B.V. and its operating companies world-wide (OmniSTAR), warrants this product to be free from defects in workmanship and material for a period of one year from the date of original sale by OmniSTAR or its authorised dealers, to the original purchaser or end user.

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REVISION HISTORY

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INTRODUCTION

The 3200LR12 receiver consists of both a 12-channel GPS receiver and a L-Band differential receiver built into a single unit. It provides differentially corrected positions at update rates up to 5 times a second through two independently configurable RS-232 I/O ports. Position accuracy is typically less than one metre and the receiver is suitable for both ground and air applications. Three LED indicator lights give operational status at a quick glance. The receiver can have a one-pulse-per-second output signal synchronised to GPS time.

The 3200LR12 receiver is easily configured using TSIP commands. Baud rate, position update rate, common NMEA string output and binary data output are among the variables which can be controlled using the TSIP commands. More detail on these commands is provided in a later section and in the View 3200 software Manual.

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GPS/DGPS Introduction

The Global Positioning System (GPS) is a reliable, continuous, all-weather navigation system, which is operated by the United States Government. At the time of writing, the space segment of GPS includes a constellation of 28 satellites, which orbit the earth at an altitude of approximately 22,000 km.

These satellites (Space Vehicles or SV's) transmit radio signals containing precise satellite time and position information. By receiving four or more of these signals a 3-dimensional position can be computed.

Although GPS provides an acceptable level of performance for some users, many applications demand a more reliable and precise position than GPS alone can provide. In such cases Differential GPS (DGPS) must be used.

The purpose of DGPS is to minimise the effects of atmospheric and satellite errors on the position determination. In order to achieve this a reference GPS receiver must be installed at a point of known co-ordinates. This receiver uses the radio signals from each of the GPS satellites, which are in view to measure so-called pseudo-ranges to these satellites. Because the exact locations of the satellites and the reference receiver are known, it is then possible to determine the difference between the actual and the expected pseudo-ranges (pseudo-range correction or PRC).

In order to provide compatibility for exchanging this correction data, a standard has been developed by the Radio Technical Commission for Maritime Services Special Committee 104. This standard is commonly known as RTCM SC-104.

When RTCM version 2.0 correction data from the reference receiver is applied to a nearby GPS receiver, the position accuracy will be substantially better than if stand-alone GPS were to be used.

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The OmniSTAR system

The 3200LR12 is one of several DGPS receivers which have been designed to work with the world-wide OmniSTAR service.

The OmniSTAR DGPS system delivers corrections from an array of reference stations, which are located all around the world (see appendix C). The RTCM correction data from these reference stations is provided to OmniSTAR's three Network Control Centres (NCC), where the corrections are decoded, checked, and repackaged in a highly efficient format for broadcast.

The OmniSTAR data is broadcast over a series of L-band communication satellites. The signal transmitted over each of these satellites contains the corrections from the reference stations in and close to the region in which this satellite can be received.

When a receiver with a valid subscription receives data through one of OmniSTAR's satellite channels it will output a differentially corrected position. The way in which the correction data from each individual reference station will be used in the position calculation depends on the user's OmniSTAR subscription.

Subscription type

The 3200LR12 supports the following OmniSTAR service:

- Virtual Base Station (VBS), where the data from multiple reference stations is used in the processor software to produce enhanced corrections for the user's location. This service provides optimal position accuracy with a minimum dependence on the user's location. The VBS service can be obtained on a continental, country or regional basis.

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The 3200LR12

General Description

The 3200LR12 is the main part of a portable system. It contains the satellite RF receiving and signal processing components. All ancillary equipment is plugged into the appropriate sockets on the receiver rear panel.

A typical 3200LR12 package will consist of the following items:

- 3200LR12 (receiver)
- User manual
- Data cable
- Power cable
- Antenna
- RF cable
- CD-ROM with View 3200 software and manual
- View3200 manual

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Options

The 3200LR12 is supplied with combined GPS and DGPS antenna, it must be plugged into the GPS socket on the rear panel of the receiver.

A system equipped with a combined GPS and DGPS antenna is illustrated in figure 1.

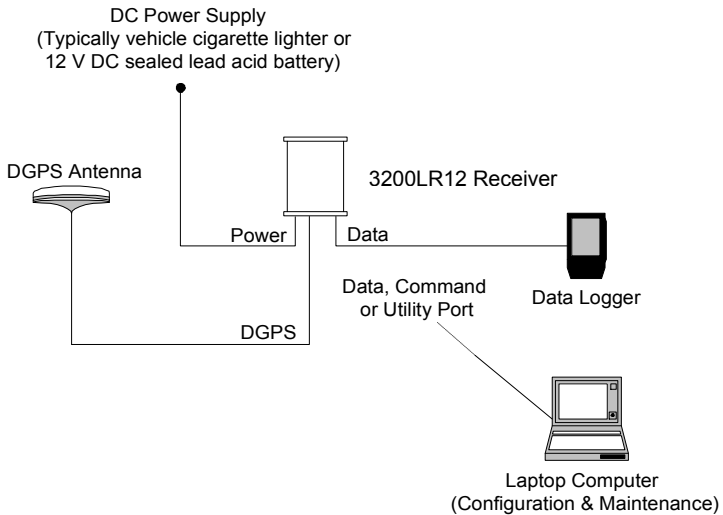


Figure 1: 3200LR12 with DGPS Antenna

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Operating considerations

The 3200LR12 has proven to be a high-quality positioning device. The accuracy that the user can obtain depends on several factors, including:

- Number of visible satellites
- Multipath
- Dilution of Precision (DOP)
- Satellite elevations
- Differential correction

Number of visible satellites

A minimum of four satellites is required to calculate a 3-dimensional position. In general it can be said that every increase in the number of visible satellites will result in an increase in the system's accuracy. As the GPS satellites orbit around the earth the number of visible satellites will change in time. The GPS constellation has been designed so as to provide a minimum of 4 visible satellites at any location at all times. The number of visible satellites can decrease due to blockage by objects such as trees and buildings.

Multipath

It is possible for satellite signals to reflect off large nearby objects such as buildings, cars or even the ground, thereby resulting in an erroneous distance measurement. This phenomenon is known as multipath. Multipath can cause significant errors in the position determination and it is therefore important to place the receiver in an environment, which is free of large reflective surfaces. It is also recommended to mount the receiver directly onto a surface, while maintaining a clear view of the sky in all directions.

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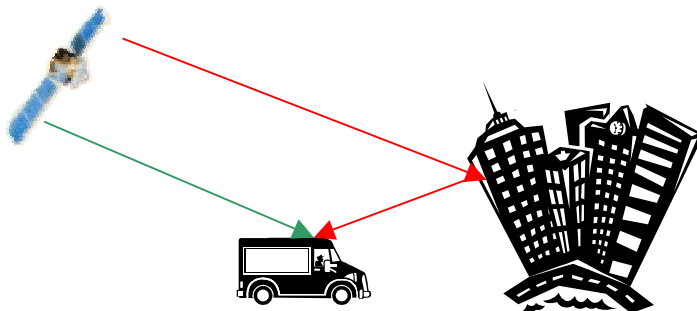


Figure 2: Multipath

Position Dilution of Precision (DOP)

The Position Dilution of Precision (PDOP) is a measure of the satellite geometry. The lower the PDOP value, the more accurate the GPS position will be. By default the 3200LR12 is configured to output position data as long as the Position Dilution of Precision does not exceed 10.

Satellite elevations

The signal from a satellite, which is low on the horizon, will travel a greater distance through the atmosphere. This results in a lower signal strength and a delayed reception, thereby causing erroneous and noisy data. By default the 3200LR12 is configured to ignore any satellites, which have an elevation angle, lower than 5°.

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Differential corrections

For accurate positioning it is essential that the differential corrections are received. In order to ensure reception of the OmniSTAR satellite signal it must be prevented that the line of sight towards the satellite is blocked by objects such as trees and buildings.

Multipath reflections can cause destructive interference, thereby significantly decreasing the signal strength. It is therefore recommended to mount the 3200LR12 directly onto a surface in a reflection free environment.

Although the 3200LR12 has been designed to provide optimal system performance under most circumstances, it is possible, due to the nature of radio communications, that system performance degrades due to local interference sources.

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GETTING STARTED

The purpose of this section is to get you started with the 3200LR12 as quickly as possible. The guide will address receiving the satellite data carrier, and then checking the functionality of the internal GPS engine fitted.

Generally when the receiver is supplied to you it will be configured for the mode and data link(s) you have subscribed to. In most cases to get up and running will be a case of connecting the appropriate cables and applying power to the system.

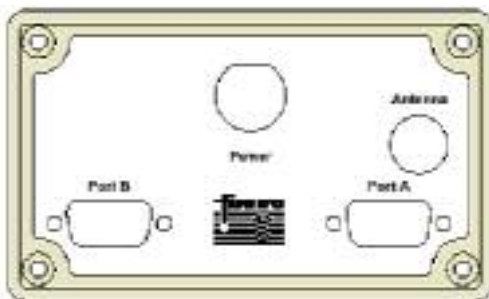


Figure 3: Bare Rear View of 3200LR12 Receiver

Initial Setup

Steps 1 through 7 pertain to all OmniSTAR receiver models.

1. Refer to the following, as you will need to assemble all the required items.
 - OmniSTAR Receiver
 - Antenna
 - Antenna Cable
 - Power Cable
 - Data Port Cable
 - Power Supply

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2. Connect the power cable to a suitable 10 V – 32 VDC power supply being sure to check correct polarity.
 - Red – Positive VDC
 - Black – Negative VDC
3. The 3200LR12 is an integrated GPS, DGPS receiver and needs only one antenna. You need to install the antenna where it has a clear 360° unobstructed view of the sky through an elevation of 5° through 90°.
4. Connect the antenna cable between the antenna and the TNC connector on rear panel.
5. Ensure the OmniSTAR power is OFF then connect the power cable into the power socket on the receiver.
6. Turn on the 3200LR12 and the Power LED will illuminate. Data LED's will illuminate when Data is present in the respective Data ports.
7. The GGA output message will indicate a non-corrected stand-alone position with a 1 (one) after the 'E' in the message when viewed on a suitable data logging device or computer.

A differentially corrected position is indicated by a 2 (two) directly after the 'E' in the GGA message from Port A.

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Figure 4: World coverage map for the OmniSTAR service



Figure 5: EA-SAT coverage in Europe



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Interfacing

Electrical Interface Description

The RF Connector is a standard TNC 50 Ohm female connector. There are 10vDC present when the unit is powered up to bias the LNA in the remote antenna. Care should be taken not to connect or disconnect the antenna while powered up.

The I/O cable connector is a standard DB 9 connector. The pin-out is defined below.

| Pin No | Name | Description |
|--------|---------------|-------------|
| 1 | Not Connected | N/A |
| 2 | Receive | Rx |
| 3 | Transmit | Tx |
| 4 | Not connected | N/A |
| 5 | Ground | GND |
| 6 | Not Connected | N/A |
| 7 | Not Connected | N/A |
| 8 | Not Connected | N/A |
| 9 | Not Connected | N/A |

This is the pin assignment for the 3200LR12 communication ports. The connector type is a 9-pin female 'D' type.

PORT A (DCE)

| | |
|---|--------|
| 1 | CANL_A |
| 2 | TXDA* |
| 3 | RXDA* |
| 4 | |
| 5 | GND* |
| 6 | |
| 7 | CTSA |
| 8 | RTSA |
| 9 | CANH_A |

PORT B (DCE)

| | |
|---|---------------|
| 1 | CANL_B |
| 2 | TXDB* |
| 3 | RXDB* |
| 4 | PPS |
| 5 | GND* |
| 6 | EVENT |
| 7 | CTSB/422B In |
| 8 | RTSB/422B Out |
| 9 | CANH_B |

*Indicates standard cable connections.

Warning: Do not use standard RS 232 cables as all connections will be made to the computer and there are non standard assignments on the pins of both ports. Use the provided Data Cables.

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Power Requirements

The unit will operate on any DC Voltage between 10 V and 32 VDC without interruption. When operational, the unit dissipates 7 W of power. The 3200LR12 can also withstand voltage surges up to 85 V. The input has reverse polarity protection, however as the negative terminal pin is also attached to the housing ground, large currents may flow to any ground attachments made to the housing. Reverse polarity must therefore be avoided to prevent damage to the vehicle supply. At Voltages below 10 Volts the unit will reset itself to prevent any data loss. At Voltages below 8.5 Volts the receiver will turn off.

Mechanical Interface

Mounting of the receiver is done with a mounting brace or brackets.

Interfacing with the 3200LR12 Receiver

The standard configuration is:

Port A: 4 string NMEA @ 1 Hz, 9600 Baud (GGA, GSA, VTG, GLL)

Port B: TSIP Binary @ 1 Hz, 9600 Baud, 8-Odd-1

The receiver will default to the below settings if the 3200LR12 is reset to defaults.

Port A: NMEA @ 9600, 8-N-1

Port B: TSIP @ 9600, 8-Odd-1

The 3200LR12 Receiver has two fully configurable RS-232 serial ports. Commands may be issued on either port and the receiver may be configured to output any of the available messages on either port. The baud rate on each port is adjustable, however the data bits, parity and stop bits are set to 8-Odd-1 for TSIP, Port B and may not be changed. These settings are necessary for the communication with the View3200 software.

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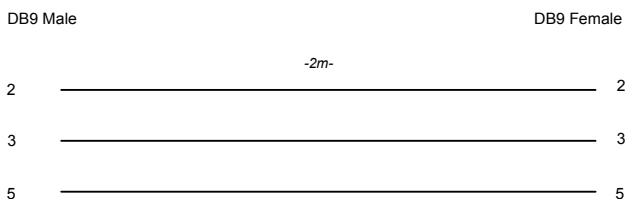
Cables

The 3200LR12 is supplied with three cables.

ANTENNA CABLE

| | | | |
|--|-----------------|-----------------|-----|
| 5 metre low loss RG58 Double shielding or equivalent | | | |
| TNC Male | | N Type Male | |
| N/A | GPS/DGPS Signal | GPS/DGPS Signal | N/A |

DATA CABLE



POWER CABLE

| 2metre Black Jacket Red & Black 2 Core Cable | | |
|--|---------------------|-------------|
| Pin # | Voltage | Wire colour |
| 1 | Positive DC Voltage | Red |
| 2 | Negative DC Voltage | Black |
| 3 | Not connected | |

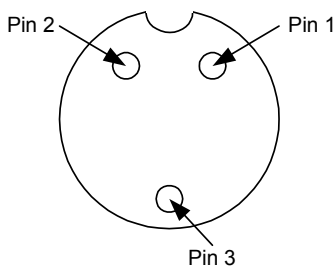


Figure 6: Mating end of Female Connector, Switchcraft EN3C3F

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LED Indicators

The 3200LR12 has three LED indicator lights. These LED lights serve as status indicators.

The 'Power' LED indicates power to the 3200LR12 and should remain solid once power is applied to the receiver. Both Data Port LED's will flash as data is transmitted from the respective ports.

The LED's will flash at the output rate of the port, one or five hertz.



Figure 7: 3200LR12 front panel

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Installation

Installation Consideration

- Determine preferred location of each unit prior to beginning installation. Consider cable length, connector attachment space (cable bend radius), stowing excess cable, moisture, chemical corrosion, vibration and heat exposure.
- Before drilling holes, consider using existing hardware and hardware locations. Avoid drilling holes that may damage other equipment (example: structural frame members, electrical cables or fluid lines).
- High vibration and high temperature locations should be avoided whenever possible.
- In application where vibration exceeds 5 G's acceleration, shock mounts are required. Refer to Customer support for mounting recommendations.
- Vehicle primary power contains voltages that may be harmful to personnel and equipment. Detach battery cable connector from battery Negative (-) terminal before attempting connection to any power terminal.

Electrical Grounding Requirements

The 3200LR12 requires a perfect ground to vehicle structure at the negative line in the receiver power input. The L-Band Receiver should read zero Ohms to where the battery negative terminal is connected to vehicle ground.

Counter Electromagnetic Force (CEMF)

A potential problem inherent in any installation of electronic systems in a vehicle is Counter Electromagnetic Force (CEMF).

CEMF is caused when relays or solenoids connected to the common vehicle DC power bus are de-energised. The voltage produced may exceed – 400 volts.

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CEMF is produced by equipment such as the following:

- Electric Fan Brakes
 - Air Conditioners
 - Starter Relays
- Electric Pump Relays

CEMF is more than sufficient to damage, or cause erratic operation of any electronic system also connected to DC power.

CEMF can be eliminated by installing Diodes at the relays and solenoids that cause the CEMF and more importantly at the Power Supply Cable connections of the 3200LR12 system. A 47 V, 5 W, Zener Diode (1N5368 or equivalent) should be connected.



Figure 8: Zener Diode Installation.

Cable Installation Considerations

- Cables must be correctly installed for optimum system operations.
- Do not route L-Band Receiver remote antenna cable with those of any other radio system cabling, as this may cause interference between both systems. If at all possible, do not run L-Band Receiver antenna cables parallel to other radio system cable closer than 30 centimetres.
- If any cables must cross; cross at a 90 degree angle. This prevents interference between systems
- Cables and I/O connectors are unique and fit only in the correct place.
- Routing cables along side power generator wires and other high noise electrical sources may cause interference.
- Do not kink or force cables into sharp bends that may damage cables and cause system failure. After installation ensure that excess cable in looped and clamped or tied safely away from any control cables, fuel lines, hydraulic lines or moving parts. When stowing over length cables, form loops not less than 150mm minimum cable bend radius.
- Cable routing must avoid high temperature exposure (example: exhaust manifold).

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Antenna Location

Antenna position is critical to system performance. These conditions must be met for proper system operations:

- Antenna must be mounted at least 1.5 metres away from transmitting antennae of any frequency. Closer positioning may cause overloading of receiver RF circuits.
- The antenna should be mounted at the highest practical point that will give a good view of the horizon and be as near to level as possible.
- The antenna must be located along the vehicle centre line or at a relevant reference point on the vehicle.

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APPENDIX A

Receiver Service Procedure

If an OmniSTAR Receiver unit fails to perform, contact the OmniSTAR office within the region, after following the procedural checks.

We wish to hear about frequently experienced problems, and your assistance will help by copying the form on the next page, filling in the details requested and faxing or mailing the form to the OmniSTAR office for on-forwarding to Product Marketing.

The most common problems are interfacing, and usually occur at installation time. If you have an interfacing connection not covered in this manual we would like to assist you and produce another technical bulletin that may assist other users in the future.

If a problem appears that you think may be caused by a system performance problem, contact the OmniSTAR office in your region for any system aberrations that may have been experienced.

We are sensitive to our customers' needs and we want to assure specified system performance at all times. There could, however, be situations where conditions are below par, such as fringe area operations, radio communication disturbance etc., and, as OmniSTAR Receiver monitors the system performance continuously, these conditions would be noted.

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APPENDIX B

Introduction NMEA 0183

NMEA 0183 is an interface protocol created by the National Marine Electronics Association. The latest release of NMEA 0183 is Version 2.1. This protocol was originally established to allow marine navigation equipment to share information. NMEA 0183 is a simple, yet comprehensive ASCII protocol, which defines both the communication interface and the data format.

This appendix provides a brief overview of the NMEA protocol and describes both the standard and optional messages offered by the Trimble BD132 GPS receiver employed in the 3200LR12 DGPS Receiver.

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NMEA 0183 Message Format

NMEA 0183 allows a single source (talker) to transmit serial data over a single twisted wire pair to one or more receivers (listeners). The NMEA 0183 protocol covers a broad array of navigational data. This is separated into discrete messages, which convey a specific set of information. The NMEA 0183 message structure is outlined below.

`$IDMSG,D1,D2,D3,D4,.....,Dn*CS[CR][LF]`

“\$” The “\$” signifies the start of message.

ID The Talker identification is a two letter mnemonic which describes the source of the navigation information. The GP identification signifies a GPS source.

MSG The message identification is a three letter mnemonic which describes the message content and the number and order of the data fields.

“,” Commas serve as delimiters for the data fields.

Dn Each message contains multiple data fields (Dn) which are delimited by commas.

“*” The asterisk serves as a checksum delimiter.

CS The checksum field contains two ASCII characters which indicate the hexadecimal value of the checksum.

[CR][LF] The carriage return [CR] and line feed [LF] combination terminate the message.

NMEA messages vary in length, but each message is limited to 79 characters or less. This length limitation excludes the “\$” and the [CR] [LF]. The data field block, including delimiters, is limited to 74 characters or less.

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NMEA 0183 Message Options

The OmniSTAR 3200LR12, when supplied with an “Trimble BD132” GPS receiver is factory configured with 4 NMEA 0183 sentences GGA, GLL, GSA and VTG. Sentences can be added or removed by the factory to a maximum of four sentences. The output rate is fixed at a 1-second interval. Faster output rates are available up to 10 times per second. There are more messages possible who are GPS receiver specific and not a NMEA 0183 standard.

| Standard | Message Sentence | Description |
|----------|------------------|---|
| | ALM | GPS Almanac Data |
| | GBS | GNSS Satellite Fault Detection |
| * | GGA | GPS Fix Data |
| * | GLL | Geographic Position – Latitude/Longitude |
| | GRS | GPS Range Residuals |
| * | GSA | GPS DOP and Active Satellites |
| | GST | GPS Pseudorange Noise Statistics |
| | GSV | GPS Satellites in View |
| | RMC | Recommended Minimum Specific GPS Data |
| * | VTG | Track Made Good and Ground Speed |
| | ZDA | Time and Date |
| | PTNLDG | DGPS Receiver Status |
| | PTNL, GGK | Time, Position, Position Type and DOP Values |
| | PTNLID | Receiver Identity |
| | PTNL5M | RTCM Special Message |

Table 1: NMEA 0183 messages available for the 3200LR12

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NMEA 0183 Message Formats

In this section each message is described in more detail.

ALM – GPS Almanac Data

The ALM message identifies the GPS week, SV health and contains the almanac for one satellite. One sentence per satellite, up to a maximum of 32.

\$GPALM,1,1,03,698,00,6ae6,1d,779f,fdef,a10d68,6469a6,7c1f62,5f5
839,*43

| Field Number | Description |
|--------------|--|
| 1 | Total number of ALM sentences for this cycle |
| 2 | Sentence sequence number |
| 3 | SV PRN number, 01 to 32 |
| 4 | GPS week number |
| 5 | SV health status |
| 6 | Eccentricity |
| 7 | Almanac reference time |
| 8 | Inclination angle |
| 9 | Rate of right ascension |
| 10 | Root of semi-major axis |
| 11 | Argument of perigee |
| 12 | Longitude of ascension node |
| 13 | Mean anomaly |
| 14 | A f0, clock parameter |
| 15 | A f1, clock parameter |

Table 2: Description of the ALM message.

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GBS – GNSS Satellite Fault Detection

The GBS sentence is used to support Receiver Autonomous Integrity Monitoring (RAIM).

\$GBS,183059.30,0.0,0.0,0.0,0.0,0.0,0.0*6F

| Field Number | Description |
|---------------------|---|
| 1 | UTC time of the GGA or GNS fix associated with this sentence. |
| 2 | Expected error in latitude. |
| 3 | Expected error in longitude. |
| 4 | Expected error in altitude. |
| 5 | ID number of most likely failed satellite. |
| 6 | Probability of missed detection for most likely failed satellite. |
| 7 | Estimate of bias, in meters, on most likely failed satellite. |
| 8 | Standard deviation of bias estimate. |

Table 3: Description of the GBS message.

NOTE:

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum rate of 1 Hz.

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GGA – GPS Fix Data

The GGA message includes time, position and fix related data for the GPS receiver.

\$GPGGA,hhmmss.s,lll.llll,a,yyyyy.yyyy,a,x,xx,x.x,x.x,M,x.x,M,x.x,xxxx

| Field Number | Description |
|--------------|--|
| 1 | UTC of Position |
| 2,3 | Latitude, N (North) or S (South). * |
| 4,5 | Longitude, E (East) or W (West). * |
| 6 | GPS Quality Indicator: 0=No GPS, 1=GPS, 2=DGPS. |
| 7 | Number of Satellites in Use. |
| 8 | Horizontal Dilution of Precision (HDOP). |
| 9,10 | Height above Mean Sea level in Meters, M = Meters. |
| 11,12 | Geoidal Separation in Meters, M = Meters. ** |
| 13 | Age of Differential GPS Data. *** |
| 14 | Differential Reference Station ID (0000 – 1023) |

Table 4: Description of the GGA message.

NOTES:

* The GGA message provides 4 decimal points of precision in non-differential mode, and 5 decimal points of accuracy in differential mode.

** Geoidal Separation is the difference between the WGS-84 earth ellipsoid and mean-sea-level (MSL).

*** Time in seconds since the last RTCM SC-104 message type 1 or type 9 update.

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GLL – Geographic Position – Latitude/Longitude

The GLL message contains the latitude and longitude of the present position, the time of the position fix and the status.

\$GPGLL,IIII.III,a,yyyyy.yyy,a,hhmmss.s,A

| Field Number | Description |
|--------------|-----------------------------------|
| 1,2 | Latitude, N (North) or S (South). |
| 3,4 | Longitude, E (East) or W (West). |
| 5 | UTC of Position. |
| 6 | Status: A = Valid, V = Invalid. |

Table 5: Description of the GLL message.

GRS – GPS Range Residuals

The GRS sentence is used to support the Receiver Autonomous Integrity Monitoring (RAIM).

\$GPGRS,220320.0,0,-0.8,-0.2,-0.1,-0.2,0.8,0.6,,,,,,*55

| Field Number | Description |
|--------------|---|
| 1 | UTC time of GGA position fix |
| 2 | Residuals |
| | 0: Residuals used to calculate position given in the matching GGA line |
| | 1: Residuals recomputed after the GGA position was computed |
| 3 to 14 | Range residuals for satellites used in the navigation solution, in meters |

Table 6: Description of the GRS message.

NOTE:

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum rate of 1 Hz.

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GSA – GPS DOP and Active Satellites

The GSA message indicates the GPS receivers operating mode and lists the satellites used for navigation and the DOP values of the position solution.

\$GPGSA,a,x,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,x,x,x,x,x,x

| Field Number | Description |
|--------------|--|
| 1 | Mode: M = Manual, A = Automatic. |
| 2 | Current Mode 1 = Fix not available, 2 = 2D fix, 3 = 3D fix. |
| 3 to 14 | PRN numbers of the satellites used in the position solution. * |
| 15 | Position Dilution of Precision (PDOP). |
| 16 | Horizontal Dilution of Precision (HDOP). |
| 17 | Vertical Dilution of Precision (VDOP) |

Table 7: Description of the GSA message.

NOTE:

* When less than 12 satellites are used, the unused fields are null.

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GST – GPS Pseudorange Noise Statistics

The GST sentence is used to support Receiver Autonomous Integrity Monitoring (RAIM).

\$GPGST,220320.0,1.3,0.8,0.5,166.1,0.8,0.5,1.6,*4F

| Field Number | Description |
|---------------------|--|
| 1 | UTC time of GGA fix |
| 2 | RMS value of the standard deviation of the range inputs to the navigation process (range inputs include pseudoranges and DGPS corrections) |
| 3 | Standard deviation of semi-major axis of error ellipse, in meters |
| 4 | Standard deviation of semi-minor axis of error ellipse, in meters |
| 5 | Orientation of semi-major axis of error ellipse, in degrees from true north |
| 6 | Standard deviation of latitude error, in meters |
| 7 | Standard deviation of longitude error, in meters |
| 8 | Standard deviation of altitude error, in meters |

Table 8: Description of the GST message.

NOTE:

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum rate of 1 Hz.

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GSV – GPS Satellites in View

The GSV sentence identifies the number of SVs in view, the PRN numbers, elevation, azimuth and SNR values.

\$GPGSV,4,1,13,02,02,213,,03,-3,000,,11,00,121,,14,13,172,05*67

| Field Number | Description |
|--------------|--|
| 1 | Total number of sentences of this type in this cycle |
| 2 | Sentence number |
| 3 | Total number of SVs visible |
| 4 | SV PRN number |
| 5 | Elevation in degrees, 90 ½ maximum |
| 6 | Azimuth, degrees from true north, 000 ½ to 359 ½ |
| 7 | SNR, 00-99 dB (null when not tracking) |
| 8-11 | Information about second SV, same format as fields 4-7 |
| 12-15 | Information about third SV, same format as fields 4-7 |
| 16-19 | Information about fourth SV, same format as fields 4-7 |

Table 9: Description of the GSV message.

NOTE:

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum rate of 1 Hz.

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RMC – Recommended Minimum Specific GPS Data

The RMC sentence identifies the UTC time, status, latitude, longitude, speed over ground (SOG), date and magnetic variation of the position fix.

```
$GPRMC,184804.00,A,3723.476543,N12202.239745,W,000.0,0.0,0,0
51196,15.6,E*7C
```

| Field Number | Description |
|--------------|--|
| 1 | Time: UTC time of the position fix in hhmmss.ss format |
| 2 | Status A: Valid V: Navigation Receiver Warning (V is output whenever the receiver suspects something is wrong) |
| 3 | Latitude coordinate |
| 4 | Latitude direction: N = North, S = South |
| 5 | Longitude coordinate |
| 6 | Longitude direction: W = West, E = East |
| 7 | Speed Over Ground (SOG) in knots (0-3 decimal places) |
| 8 | Track Made Good, True, in degrees |
| 9 | Date in dd/mm/yy format |
| 10 | Magnetic Variation in degrees |
| 11 | Direction of magnetic variation E: Easterly variation from True course (subtracts from True course) W: Westerly variation from True course (adds to True course) |
| 12 | Mode Indication A: Autonomous D: Differential N: Data not valid |

Table 10: Description of the RMC message.

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VTG – Course Over Ground and Ground Speed

The VTG sentence identifies the actual track made good and speed over ground.

\$GPVTG,0,T,,0.00,N,0.00,K*33

| Field Number | Description |
|---------------------|---|
| 1 | Track made good |
| 2 | Fixed text 'T' shows that track made good is relative to true north |
| 3 | Not used |
| 4 | Not used |
| 5 | Speed over ground in knots (0-3 decimal places) |
| 6 | Fixed text 'N' shows that speed over ground is in knots |
| 7 | Speed over ground in kilometers/hour (0-3 decimal places) |
| 8 | Fixed text 'K' shows that speed over ground is in kilometers/hour |

Table 11: Description of the VTG message.

NOTE:

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum rate of 1 Hz.

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ZDA – Time and Date

The ZDA message contains UTC, the day, the month and the year of the local time zone.

\$GPZDA,hhmmss.s,xx,xx,xxxx,xx,xx

| Field Number | Description |
|--------------|---|
| 1 | UTC. |
| 2 | Day (0 – 31). |
| 3 | Month (0 – 12). |
| 4 | Year. |
| 5 | Local Zone Description Hours (\pm 13 Hours). * |
| 6 | Local Zone Description Minutes. |

Table 12: Description of the ZDA message.

NOTES:

* Local zone description is the number of whole hours added to local time to obtain UTC. The zone description is always negative for eastern longitudes. Fields 5 and 6 are Null fields in the "Trimble BD132". A GPS receiver cannot independently identify the local time zone offsets.

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum rate of 1 Hz.

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PTNLDG –DGPS Receiver Status

The PTNLDG sentence is a sentence for identifying the DGPS receiver channel strength, channel SNR, channel frequency, channel bit rate, channel number, channel tracking status, RTCM source and channel performance indicator for satellite DGPS.

\$PTNLDG,xxx.x,xx.x,xxxxxxx.x,xxxxx,xx,x,x,x,xx*xx

The PTNLDG sentence fields are defined in free format with the maximum number of characters in the field indicated in above (i.e. 25 bps displayed as xxx,25,xxx instead of xxx,00025,xxx). Additionally, if a channel is disabled, the channel fields may be null fields (commas only). If more than one channel is available, the sentence should be repeated for each channel.

| Field Number | Description |
|--------------|---|
| 1 | Channel signal strength, in 1 dB μ V/m. This is the ADC input voltage level. |
| 2 | Channel signal to noise (SNR) level, in dB |
| 3 | Channel frequency, in kHz |
| 4 | Channel bit rate, in bits per second (bps) |
| 5 | Channel number, 0-99 |
| 6 | Channel tracking status 0: Channel idle 1: Wideband FFT search 2: Searching for signal 3: Channel has acquired signal 4: Channel has locked on signal 5: Channel disabled |
| 7 | Specified channel is used as RTCM source 0: Not used 1: Used |
| 8 | Channel tracking performance indicator. This is the time since the last sync, in tenths of seconds ranging from 0-255 |

Table 13: Description of the PTNLDG message.

NOTE:

* Because the contents of this NMEA message do not change significantly during a 1-second interval, the receiver outputs this message at a maximum of 1 Hz.

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PTNL,GGK – Time, Position, Position Type and DOP Values

\$PTNL,GGK,172814.00,071296,3723.46587704,N,12202.26957864
,W,3,06,1.7,EHT-6.777,M*48

| Field Number | Description |
|--------------|--|
| 1 | UTC of position fix, in hhmmss.ss format |
| 2 | UTC Date of position, in mmdyy format |
| 3 | Latitude, in degrees and decimal minutes (for example, dddmm.mmmmmm) |
| 4 | Direction of latitude: N: North S: South |
| 5 | Longitude, in degrees and decimal minutes (for example, dddmm.mmmmmm) |
| 6 | Direction of Longitude: E: East W: West |
| 7 | GPS Quality indicator: 0: Fix not available or invalid 1: Autonomous GPS fix 4: Differential, code phase only solution (DGPS) |
| 8 | Number of satellites used in GPS solution |
| 9 | DOP of fix |
| 10 | Ellipsoidal height of fix (antenna height above ellipsoid) |
| 11 | M: Ellipsoidal height is measured in meters |

Table 14: Description of the PTNL,GGK message.

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PTNLID –Receiver Identity

The PTNLID sentence is a sentence for identifying the receiver's machine ID, product ID, major and minor release numbers and firmware release date.

\$PTNLID,097,01,xxx,xxx,DD/MM/YY*XX

| Field Number | Description |
|---------------------|---|
| 1 | Machine ID |
| 2 | Product ID |
| 3 | Major firmware release number |
| 4 | Minor firmware release number |
| 5 | Firmware release date, in DD/MM/YY format |

Table 15: Description of the PTNLID message.

NOTE:

* The PTNLID sentence is, if enabled, output every 30 seconds.

PTNLISM – RTCM special message

The PTNLISM sentence is a sentence for identifying the Reference Station ID and the ASCII Text message included in a RTCM Type 16 Special Message. The PTNLISM message is generated anytime a RTCM stream receives a valid Type 16 Special Message.

\$PTNLISM,0022,This is a message,*XX

| Field Number | Description |
|---------------------|---|
| 1 | Reference Station ID number, ranging from 0 to 1023. Leading zeros must be added to fill 4-digit field. |
| 2 | ASCII text message sentence contained within the Type 16 RTCM message. |

Table 16: Description of the PTNLISM message.

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APPENDIX C

List of communication satellites

The following table presents a list of L-band communication satellites, which will enable you to use your 3200LR12 over the entire world (depending on your subscription type you might only be entitled to a restricted area).

Table 17: World-wide satellite frequencies and baud rates

| Satellite Channel | Frequency (MHz) | Baud Rate |
|-------------------|-----------------|-----------|
| EA-SAT | 1535.1525 | 1200 |
| AF-SAT | 1535.0800 | 1200 |
| MSV-Central | 1534.7410 | 1200 |
| MSV-East | 1530.3590 | 1200 |
| MSV-West | 1536.7820 | 1200 |
| AP-SAT | 1535.1375 | 1200 |
| AM-SAT | 1535.1375 | 1200 |

The coverage-area of each satellite and its reference stations are displayed in the following figures.

Figure 9: Reference stations and coverage area per satellite

AF-SAT



EA-SAT



AP-SAT



AM-SAT



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APPENDIX D

List of reference stations

The following tables present the current list of reference stations, which are broadcast over the different satellites. Check www.surveyplanner.com for the latest updates of these lists.

Table 18: Reference stations on EA-SAT

| Nr | Station | ID | VBS | HP |
|----|-------------------------------|-----|-----|-----|
| 4 | Aberdeen, Scotland | 571 | YES | YES |
| 1 | Abu Dhabi, UAE | 016 | YES | YES |
| 3 | Bahrain | 260 | YES | YES |
| 7 | Baku, Azerbaijan | 400 | YES | YES |
| 8 | Cairo | 300 | YES | YES |
| 9 | Dakar | 144 | YES | YES |
| 10 | Faro, Portugal | 371 | YES | YES |
| 11 | Istanbul, Turkey | 410 | YES | YES |
| 24 | Kharkiv, Russia | 500 | YES | YES |
| 2 | Kuwait | 290 | YES | YES |
| 12 | Leidschendam, The Netherlands | 521 | YES | YES |
| 13 | Malta | 351 | YES | NO |
| 14 | Ny Alesund, Spitsbergen | 101 | YES | NO |
| 15 | Pointe-Noire, Congo | 045 | YES | NO |
| 16 | Rogaland, Norway | 580 | YES | YES |
| 17 | Sao Tome, Sao Tome | 011 | YES | NO |
| 18 | Torshavn, Faroes | 620 | YES | YES |
| 19 | Toulouse, France | 431 | YES | YES |
| 20 | Tromso, Norway | 690 | YES | YES |
| 21 | Vardo, Norway | 114 | YES | NO |
| 23 | Vienna, Austria | 480 | YES | YES |
| 24 | Visby, Sweden | 229 | YES | NO |
| 25 | Lagos, Nigeria | 060 | YES | NO |
| 26 | Las Palmas, Canaries-Sp | 280 | YES | NO |
| 27 | Luanda, Angola | 095 | YES | NO |
| 28 | Shanon, Ireland | 530 | YES | YES |
| 29 | Trondheim, Norway | 632 | YES | YES |
| 30 | Visby, Sweden | 576 | NO | YES |

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Table 17: Reference stations on AF-SAT

| Nr | Station | ID | VBS | HP |
|----|------------------------------|-----|-----|-----|
| 1 | Abidjan, Ivory Coast | 050 | YES | NO |
| 2 | Blantyre, Malawi | 155 | YES | NO |
| 3 | Cape Town, South Africa | 335 | YES | NO |
| 4 | Dakar, Senegal | 144 | YES | NO |
| 5 | Douala, Cameroon | 043 | YES | YES |
| 6 | Durban, South Africa | 305 | YES | NO |
| 7 | Faro, Portugal | 371 | YES | NO |
| 8 | Lagos, Nigeria | 060 | YES | NO |
| 9 | Las Palmas, Canaries | 280 | YES | NO |
| 10 | Luanda, Angola | 095 | YES | YES |
| 11 | Nairobi, Kenya | 015 | YES | NO |
| 13 | Pointe-Noire, Congo | 045 | YES | YES |
| 14 | Port Elizabeth, South Africa | 337 | YES | NO |
| 15 | Rogaland, Norway | 580 | YES | YES |
| 16 | Sao Tome, Sao Tome | 011 | YES | YES |
| 17 | Walvis Bay, Namibia | 235 | YES | NO |

Table 18: Reference stations on AP-Sat

| Nr | Station | ID | VBS | HP |
|----|-------------------------|-----|-----|-----|
| 1 | Auckland, NZ | 022 | YES | NO |
| 2 | Karratha, Australia | 215 | YES | NO |
| 3 | Darwin, Australia | 125 | YES | NO |
| 4 | Broome, Australia | 185 | YES | NO |
| 9 | Asahikawa, Japan | 261 | YES | NO |
| 10 | Singapore | 010 | YES | YES |
| 11 | Miri, Malaysia | 042 | YES | YES |
| 12 | Vung Tua, Vietnam | 012 | YES | YES |
| 13 | Hong Kong | 220 | YES | NO |
| 14 | Seoul, S. Korea | 370 | YES | NO |
| 15 | Kota Kinabalu, Malaysia | 061 | YES | NO |

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| | | | | |
|----|------------------------|-----|-----|-----|
| 16 | Bali, Indonesia | 096 | YES | YES |
| 17 | Mumbai-Arvi, India | 191 | YES | YES |
| 19 | Subic Bay, Phillipines | 151 | YES | NO |
| 20 | Kuwait | 290 | YES | NO |
| 21 | Abu Dhabi, UAE | 016 | YES | NO |
| 23 | Kuantan, Malaysia | 041 | YES | NO |
| 25 | Bangkok, Thailand | 141 | YES | YES |
| 26 | Chennai, India | 131 | YES | NO |
| 27 | Bathurst, Australia | 336 | YES | NO |
| 28 | Kalgoorlie, Australia | 315 | YES | NO |
| 31 | Melbourne, Australia | 385 | YES | NO |
| 32 | Okinawa, Japan | 261 | YES | NO |
| 33 | Platong, Thailand | 018 | YES | NO |
| 34 | Sakhalin, Russia | 510 | YES | NO |
| 35 | Bahrain, Bahrain | 260 | YES | NO |

Table 19: Reference stations on AM-Sat

| Nr | Station | ID | VBS | HP |
|----|-------------------------|-----|-----|-----|
| 1 | Houston, Texas | 100 | YES | YES |
| 2 | Cocoa Beach, Florida | 120 | YES | YES |
| 3 | Long Island, New York | 333 | YES | YES |
| 4 | Carmen, Mexico | 110 | YES | YES |
| 5 | Punta Arenas, Chile | 210 | YES | NO |
| 6 | Guayaquil, Ecuador | 202 | YES | NO |
| 7 | Rio de Janeiro, Brazil | 225 | YES | YES |
| 8 | St. Johns, Newfoundland | 470 | YES | YES |
| 9 | Dartmouth, Nova Scotia | 440 | YES | NO |
| 10 | Recife, Brazil | 075 | YES | NO |
| 11 | Port Of Spain, Trinidad | 111 | YES | YES |
| 12 | Caracas, Venezuela | 112 | YES | YES |
| 13 | Belem, Brazil | 017 | YES | NO |
| 14 | Caymen, Grand Cayman | 192 | YES | YES |

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| | | | | |
|----|-------------------------|-----|-----|-----|
| 15 | Honolulu, USA | 210 | YES | NO |
| 16 | Curtiba, Brazil | 257 | YES | YES |
| 17 | Pensacola, USA | 301 | YES | YES |
| 18 | Vitoria, Brazil | 205 | YES | YES |
| 19 | Mercedes, USA | 263 | YES | YES |
| 20 | Buenos Aires, Argentina | 345 | YES | NO |

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APPENDIX F

3200LR12 - Technical Specifications

Standard Features

- Submetre differential GPS accuracy
- Satellite L-band differential capability
- 12 Channel, parallel tracking, L1 C/A code with carrier phase filtered measurements
- <2 second acquisition and reacquisition time, typical
- Two programmable RS-232 serial ports
- RTCM SC-104 input
- NMEA-0813 output

Inputs and Outputs

| | |
|------------------------|------------------------------|
| Serial Ports : | Command, Data |
| Electrical Interface : | RS-232-C |
| Data Rates : | 4800, 9600, 19200, 38400 |
| Message Rate : | Typically 1-2 seconds output |
| Plug Types : | DB-9 connectors |
| RF Input to Receiver : | TNC |
| Power Connector : | 3 pin snaplock |

Optional Features

- Everest multipath reduction.
- 10Hz update rate

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Technical Specifications

| | |
|------------------------------|--|
| General | 12 parallel channels Tracks up to 12 satellites, L1 GPS L-band satellite differential correction |
| Update Rate | 1Hz standard, 10 Hz optional |
| Differential Accuracy | Less than 1 metre horizontal RMS Assumes at least 5 satellites, PDOP less than 4 and RTCM SC-104. |
| Time to first fix | <30 seconds, typical |
| NMEA messages | ALM, GGA*, GLL, GSA*, GSV, VTG*, ZDA*, RMC, GRS, GBS, GST, MSS, PTNLID, PTNLDG, PTNLMS, PTNL/GGK |
| Power | 5 Watts, max @ 10 to 32VDC |

Physical Characteristics

| | |
|-------------------------|-------------------------------|
| Weight (approx.) | 0.75kg |
| Display | 3 LED indicators |
| Control | Power switch and Command Port |

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Appendix G

OmniSTAR subscription agreement form

The form is necessary to apply for a new OmniSTAR subscription for your 3200LR12 receiver. And can be found on our website: www.omnistar.nl